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# About solvability of the matrix equation AX = B over Bezout domains

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Let R be a Bezout domain with identity  $e \neq 0$ , i.e. R is an integral domain in which every finite generated ideal is principal. Further, let  $R_{m,n}$  denote the set of  $m \times n$  matrices over R, and  $GL(n, \mathbf{R})$  be the set of  $n \times n$  invertible matrices over  $\mathbf{R}$ . In what follows,  $I_n$  is the identity  $n \times n$ matrix,  $0_{m,k}$  is the zero  $m \times k$  matrix,  $d_i(A) \in \mathbb{R}$  is an ideal generated by the *i*-th order minors of the matrix  $A \in \mathbb{R}_{m,n}$ ,  $i = 1, 2, \dots, \min\{m, n\}$ .

Let  $A \in \mathbb{R}_{m,n}$  and  $B \in \mathbb{R}_{m,k}$  be nonzero matrices. Consider the nonhomogeneous matrix equation

$$AX = B, (1)$$

where X is unknown matrix in  $R_{n,k}$ . Denote by  $A_B = \begin{bmatrix} A & B \end{bmatrix} \in R_{m,n+k}$  the extended matrix of the linear equations (1). It is known (see [1], [3], [4], [6]) that the equation (1) over a Bezout domain R is solvable if and only if rank  $A = \operatorname{rank} A_B = r$  and  $d_i(A) = d_i(A_B)$  for all  $i = 1, 2, \dots, r$ .

The problem of solvability of the equation (1) has drawn the attention of many mathematicians (see [1]–[12] and references therein). This is explained not only by the theoretical interest to this problem ([1], [3], [4], [6], [8]–[11]), but also by the existence of numerous applied problems connected with the necessity of solution of linear matrix equations ([2], [5], [7], [12]). It may be noted, that the equation (1) over Bezout domains is important in automatic control theory [2].

1. On application of the Hermite Normal Form. In the Bezout domain R we fix a set of non-associated elements R. Every non-associated element  $a \in R$  we associated with a complete system of residues modulo ideal (a). Let  $A \in \mathbb{R}_{m,n}$  and rank A = r. Further, we assume that the first row of the matrix A is nonzero. For the matrix A there exists  $W \in GL(n, \mathbb{R})$  such that

$$AW = H_A = \begin{bmatrix} H_1 & 0_{m_1, n-1} \\ H_2 & 0_{m_2, n-2} \\ \vdots & \ddots & \vdots \\ H_r & 0_{m_r, n-r} \end{bmatrix} = \begin{bmatrix} H(A) & 0_{m, n-r} \end{bmatrix}$$

is a lower block-triangular matrix, where  $H(A) \in \mathbb{R}_{m,r}$ ,  $H_1 = \begin{bmatrix} h_1 \\ * \end{bmatrix} \in \mathbb{R}_{m_1,1}$ ,  $H_2 = \begin{bmatrix} h_{21} & h_2 \\ * & * \end{bmatrix} \in \mathbb{R}_{m_2,2}$ , ...,  $H_r = \begin{bmatrix} h_{r_1} & \dots & h_{r,r-1} & h_r \\ * & * & * \end{bmatrix} \in \mathbb{R}_{r,r}$  and  $m_1 + m_2 + \dots + m_r = m$ . The elements  $h_i$  belong to the set of new ages i + 1.

$$R_{m_2,2}, \ldots, H_r = \begin{bmatrix} h_{r1} & \ldots & h_{r,r-1} & h_r \\ * & * & * \end{bmatrix} \in R_{r,r} \text{ and } m_1 + m_2 + \cdots + m_r = m.$$
 The elements  $h_r$ 

belong to the set of non-associated elements  $\widetilde{\mathbf{R}}$  for all  $i=1,2,\ldots,r$ . Moreover, in the first rows  $|h_{i1} \dots h_{i,i-1}|$  of the matrices  $H_i$ ,  $i \geq 2$ , the elements  $h_{ij}$  belong to a complete system of residues modulo ideal  $(h_i)$  for all  $j=1,2,\ldots,i-1$ . The lower block-triangular matrix  $H_A$  is called the (right) Hermite normal form of the matrix A and it is uniquely defined for A (see [3]).

In this parch we propose necessary and sufficient conditions of solvability for the equation (1) over a Bezout domain in terms of the Hermite normal forms of  $m \times (n+k)$  matrices  $A = 0_{m,k}$ and  $[A \ B]$ . A method for finding its solutions is also given. In what follows, we assume that the fest row of the matrix A is nonzero.

**Theorem 1.** Let  $A \in \mathbb{R}_{m,n}$  and  $B \in \mathbb{R}_{m,k}$ . The matrix equation AX = B is solvable over a Bezout domain R if and only if the Hermite normal forms of matrices  $[A \quad 0_{m,k}]$  and  $[A \quad B]$  are coincide.

It is easy to see that matrix equation (1) is solvable over a Bezout domain R if and only if the matrix equation H(A)Y = B is solvable over R. Let  $Y_0 \in \mathbb{R}_{r,k}$  be the solution of H(A)Y = B.

- Then for arbitrary matrix  $P \in \mathbb{R}_{n-r,k}$  the matrix  $X_P = W^{-1} \begin{bmatrix} Y_0 \\ P \end{bmatrix}$  is a general solution of equation (1). Theoretically speaking, the solution  $X_0 = W^{-1} \begin{bmatrix} Y_0 \\ 0_{m-r,n} \end{bmatrix}$  of equation (1) can be written as the matrix expression  $X_0 = TX_P$ , where  $T \in \mathbb{R}_{n,n}$ . Thus,  $X_P$  is the right divisor of  $X_0$  for an arbitrary matrix  $P \in \mathbb{R}_{n,n}$ . arbitrary matrix  $P \in \mathbb{R}_{n-r,k}$ . Given the solution  $X_0$ , we determine all possible ranks of other solutions of the equation (1), i.e.  $\operatorname{rank} B \leq \operatorname{rank} X_P \leq n + \operatorname{rank} B - \operatorname{rank} A$ .
- 2. A method of matrix transformations. In this part we apply matrix transformations for established conditions under which the equation (1) is solvable.

Let  $A \in \mathcal{R}_{m,n}$  and  $B \in \mathcal{R}_{m,k}$  be nonzero matrices and let rank  $A = r \geq 1$ . For A there exist matrices  $U \in GL(m, \mathbb{R})$  and  $V \in GL(n, \mathbb{R})$  such that  $UAV = \begin{bmatrix} C & 0_{r,n-r} \\ 0_{m-r,r} & 0_{m-r,n-r} \end{bmatrix}$ , where  $C \in \mathcal{R}_{r,r}$ . It is clear that  $\det C = c \neq 0$ . In what follows  $C^* = \operatorname{Adj} C$  means the classical adjoint matrix of the matrix C, i.e.  $C^*C = cI_r$ . Based on the above, we obtain the following theorem.

**Theorem 2.** The matrix equation AX = B is solvable over a Bezout domain R if and only if

 $UB = \begin{bmatrix} D \\ 0_{m-r,k} \end{bmatrix}, \text{ where } D \in \mathbb{R}_{r,k}, \text{ and } C^*D = cG, \text{ where } G \in \mathbb{R}_{r,k}.$ If the equation AX = B is solvable, then for arbitrary matrix  $Q \in \mathbb{R}_{m-r,k}$  the matrix  $X_Q = U^{-1} \begin{bmatrix} G \\ Q \end{bmatrix}$  is a general solution of equation AX = B.

From Theorem 2 we obtain the following comment. Let  $A, B \in \mathbb{R}_{m,n}$  be nonzero matrices and let rank A < n. Suppose the matrix equation AX = B is solvable and  $X_Q \in \mathbb{R}_{n,n}$  is its general solution. Then AX = B has solutions  $\widetilde{X}_i \in \mathbb{R}_{n,n}$ ,  $i = 1, 2, \ldots$ , such that  $X_Q = \widetilde{X}_i T_i$ , where  $T_i \in \mathbf{R}_{n,n}$ .

Presented results above can be extended to linear nonhomogeneous equations over commutative rings of a more general algebraic nature.

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