

International  
Scientific Conference



Algebraic  
and Geometric  
Methods  
of Analysis

27-30 May 2024  
Odesa, Ukraine

The purpose of this conference is to bring together researchers in geometry, topology, algebra, analysis and dynamical systems and to provide for them a forum to present their recent work to colleagues from different nationalities. This way we aim to stimulate discussion about the latest findings in geometrical and topological methods in analysis and to increase international collaboration.

The conference continues the traditional annual conference «Geometry in Odesa» holding from 2004, and hosted by Odesa National University of Technology (Odesa National Academy of Food Technologies till 2021). From 2017 the conference was renamed to «Algebraic and geometric methods of analysis» (AGMA).

The Conference languages: Ukrainian and English.

#### LIST OF TOPICS

- Algebraic methods in geometry
- Differential geometry in the large
- Geometry and topology of differentiable manifolds
- General and algebraic topology
- Dynamical systems and their applications
- Geometric and topological methods in natural sciences
- Geometric problems in mathematical analysis

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We also proved geodesical convexity of 1-foci ball, which is a hyperbolic ball, with geometrical methods.

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## A retraction from the space of pseudometrics to the space of ultrapseudometrics

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**Definition 1.** A **pseudometric** on a set  $X$  is a function  $d : X \times X \rightarrow \mathbb{R}$  that satisfies the following properties for all  $x, y, z \in X$ :

- (1) **Non-negativity**:  $d(x, y) \geq 0$ .
- (2) **Identity of indiscernibles**:  $d(x, x) = 0$ . (However, it is not required that  $d(x, y) = 0$  implies  $x = y$ , which differentiates a pseudometric from a metric.)
- (3) **Symmetry**:  $d(x, y) = d(y, x)$ .
- (4) **Triangle inequality**:  $d(x, z) \leq d(x, y) + d(y, z)$ .

An **ultrapseudometric** is a type of distance function defined on a set that generalizes the notion of a metric, incorporating properties specific to ultrametrics and pseudometrics. Formally:

**Definition 2.** An ultrapseudometric  $d$  on a set  $X$  is a function  $d : X \times X \rightarrow \mathbb{R}$  that satisfies the above properties of **non-negativity**, **identity of indiscernibles**, and **symmetry**, but the **triangle inequality** is satisfied in a stronger form:

(4) **Strong triangle inequality (Ultrametric inequality)**[1] : for all  $x, y, z \in X$

$$d(x, z) \leq \max\{d(x, y), d(y, z)\}$$

We denote with  $\mathcal{P}f(X)$  the set of all pseudometrics on a fixed set  $X$ , and  $\mathcal{UP}f(X)$  is its subset consisting of all ultrapseudometrics on  $X$ .

**Theorem 3.** *There is a non-expanding w.r.t. the uniform convergence metric retraction  $\mathcal{P}f(X) \rightarrow \mathcal{UP}f(X)$*

We rely on the following lemmas.

**Lemma 4.** *For each pseudometric  $d : X \times X \rightarrow \mathbb{R}$  and a subset  $A \subset X$  the function  $d_A : X \times X \rightarrow \mathbb{R}$  with the formula*

$$d_A(x, y) = \begin{cases} 0, & x, y \in A \text{ or } x, y \notin A, \\ d(A, X \setminus A), & x \in A, y \notin A \text{ or } x \notin A, y \in A, \end{cases} \quad x, y \in X,$$

is an ultrapseudometric such that  $d_A \leq d$ .

**Proof.** Non-negativity, symmetry, and identity of indiscernibles clearly hold. The only not so trivial part is the strong triangle inequality.[2]

- If all three points are in  $A$  or all three are not in  $A$ :  $d_A(x, z) = 0 \leq \max\{0, 0\}$ .
- If  $x, y \in A$  and  $z \notin A$  (or vice versa):  $d_A(x, y) = 0$ ,  $d_A(y, z) = d(A, X \setminus A)$ ,  $d_A(x, z) = d(A, X \setminus A)$ , hence  $d_A(x, z) \leq \max\{0, d(A, X \setminus A)\}$ .
- If  $x \in A$ ,  $y \notin A$ , and  $z \in A$  (or vice versa):  $d_A(x, y) = d(A, X \setminus A)$ ,  $d_A(y, z) = d(A, X \setminus A)$ ,  $d_A(x, z) = 0$ , hence  $d_A(x, z) \leq \max\{d(A, X \setminus A), d(A, X \setminus A)\}$ .

To compare  $d_A$  and  $d$ :

- If  $x, y \in A$  or  $x, y \notin A$ :  $d_A(x, y) = 0 \leq d(x, y)$ .
- If  $x \in A$  and  $y \notin A$  (or vice versa):  $d_A(x, y) = d(A, X \setminus A) \leq d(x, y)$ .

□

**Lemma 5.** *For each pseudometric  $d : X \times X \rightarrow \mathbb{R}$  the function  $\bar{d} : X \times X \rightarrow \mathbb{R}$  such that*

$$\bar{d}(x, y) = \sup\{d_A(x, y) \mid A \subset X\}, \quad x, y \in X,$$

is the greatest ultrapseudometric on  $X$  not exceeding  $d$ .

**Proof.** (1) **Ultrapseudometric properties of  $\bar{d}$ :**

(a) **Symmetry:**

$$\bar{d}(x, y) = \sup\{d_A(x, y) \mid A \subseteq X\} = \sup\{d_A(y, x) \mid A \subseteq X\} = \bar{d}(y, x)$$

since  $d_A$  is symmetric for all  $A \subseteq X$ .

(b) **Non-negativity and zero distance:**

$$\bar{d}(x, y) \geq 0$$

and

$$\bar{d}(x, x) = \sup\{d_A(x, x) \mid A \subseteq X\} = 0$$

since  $d_A(x, x) = 0$  for all  $A \subseteq X$ .

(c) **Ultrametric inequality:** For all  $x, y, z \in X$ :

$$\bar{d}(x, z) = \sup\{d_A(x, z) \mid A \subseteq X\}$$

and

$$\bar{d}(x, z) \leq \sup\{\max\{d_A(x, y), d_A(y, z)\} \mid A \subseteq X\} \leq \max\{\bar{d}(x, y), \bar{d}(y, z)\}$$

since  $d_A$  satisfies the ultrametric inequality for all  $A \subseteq X$ .

(2) **Comparison  $\bar{d} \leq d$ :** For each  $A \subseteq X$ , we have  $d_A \leq d$ , thus:

$$\bar{d}(x, y) = \sup\{d_A(x, y) \mid A \subseteq X\} \leq d(x, y).$$

(3) **Greatest ultrapseudometric not exceeding  $d$ :** Suppose there exists another ultrapseudometric  $d'$  on  $X$  such that  $d' \leq d$  and  $d' \geq \bar{d}$ . Then, for any  $A \subseteq X$ ,  $d_A \leq d'$ , hence:

$$\bar{d} = \sup\{d_A \mid A \subseteq X\} \leq d'.$$

Therefore,  $\bar{d}(x, y) = \sup\{d_A(x, y) \mid A \subseteq X\}$  is the greatest ultrapseudometric on  $X$  not exceeding  $d$ .  $\square$

We will discuss efficient algorithms for calculation of  $\bar{d}$  for a given  $d$  on a finite set  $X$ .

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## Action of derivations on polynomials and on Jacobian derivations

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Let  $\mathbb{K}$  be an arbitrary field of characteristic zero. Denote by  $A := \mathbb{K}[x_1, \dots, x_n]$  the polynomial ring, and by  $R := \mathbb{K}(x_1, \dots, x_n)$  the field of rational functions in  $n$  variables, respectively. A  $\mathbb{K}$ -linear map  $D : A \rightarrow A$  is called a  $\mathbb{K}$ -derivation on  $A$  if  $D(fg) = D(f)g + fD(g)$  for any  $f, g \in A$ . The vector space  $W_n(\mathbb{K})$  (over  $\mathbb{K}$ ) of all  $\mathbb{K}$ -derivation is a Lie algebra with respect to the Lie bracket  $[D_1, D_2] = D_1D_2 - D_2D_1$ ,  $D_1, D_2 \in W_n(\mathbb{K})$ . Recall that every element  $D \in W_n(\mathbb{K})$  can be uniquely written in the form

$$D = f_1 \frac{\partial}{\partial x_1} + \dots + f_n \frac{\partial}{\partial x_n}, f_i \in A.$$

The latter means that  $W_n(\mathbb{K})$  is a free module of rank  $n$  over  $A$  with the free generators  $\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n}$  (see, for example [3], [4]).

Every element  $D$  from  $W_n(\mathbb{K})$  acts naturally on polynomials from  $A$  and on  $W_n(\mathbb{K})$  itself (by multiplication). Recall that a polynomial  $f \in A$  is a Darboux polynomial for a derivation  $D \in W_n(\mathbb{K})$  if  $D(f) = \lambda f$  for some  $\lambda \in A$ , the polynomial  $\lambda$  is called a cofactor for  $D$ . One can consider the Darboux polynomials as "eigenvectors" for the derivation  $D$  with polynomial "eigenvalues". These (non-constant) polynomials (if they do exist) play significant role in theory of differential

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